Abstract Cores in Implicit Hitting Set MaxSAT solving

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Joint work with Fahiem Bacchus Many thanks also to Matti Järvisalo and Ruben Martins for contributions to slides

Who am I?

- Post Doctoral researcher at the University of Helsinki
 - Constraint Reasoning and Optimisation Group led by Prof. Matti Järvisalo.
- Defended PhD thesis on algorithms and applications of MaxSAT in 2018
- Visits to Melbourne (Prof. Stuckey) and Toronto (Prof. Bacchus)
- Research focus atm. on declarative methods for solving NP-hard optimisation problems.



Maximum Satisfiability

$Maximum \ Satisfiability - MaxSat$

Exact Boolean optimization paradigm

- Builds on the success story of Boolean satisfiability (SAT) solving
- ▶ Great recent improvements in practical solver technology
- ▶ Expanding range of real-world applications

Offers an alternative to e.g. integer programming

- Solvers provide provably optimal solutions
- Propositional logic as the underlying declarative language: especially suited for inherently "Boolean" optimization problems

Implicit Hitting Set based Maximum Satisfiability

The IHS based approach to MaxSat

One of the central methods for exactly solving instances arising in real-world domains.

- Decouples MaxSat into separate reasoning (i.e. core-extraction) and optimization steps.
- ▶ Avoids increasing the complexity of SAT-calls.
- ▶ Top positions in annual evaluations since 2015
- IHS framework instantiated in various applications [Karp, 2010; Saikko, Wallner, and Järvisalo, 2016b; Fazekas, Bacchus, and Biere, 2018; Ignatiev, Previti, Liffiton, and Marques-Silva, 2015].

Outline

- 1. Motivation and Basic Concepts
- 2. (Short) Overview of MaxSAT solving Algorithms.
- 3. The implicit hitting set approach to MaxSAT
 - ▶ With Correction Sets
 - ▶ With Bounds.
- 4. Abstract Cores

Success of SAT

The Boolean satisfiability (SAT) Problem Input: A propositional logic formula F. Task: Is F satisfiable?

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SAT is a Great Success Story

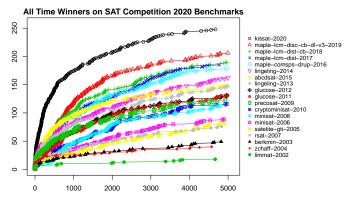
Not merely a central problem in theory:

Remarkable improvements since mid 90s in SAT solvers: practical decision procedures for SAT

- ▶ Find solutions if they exist
- Prove non-existence of solutions

SAT Solvers

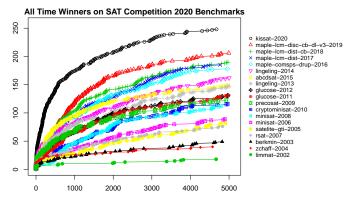
From 100s of variables and constraints (early 90s) up to 10M variables and constraints. (21st century).



Plot provided by Armin Biere

SAT Solvers

From 100s of variables and constraints (early 90s) up to 10M variables and constraints. (21st century).



Plot provided by Armin Biere

Core NP search procedures for solving various types of computational problems

Optimization

Most real-world problems involve an optimization component Examples:

▶ Find a shortest path/plan/execution/...to a goal state

▶ Planning, model checking, ...

▶ Find a smallest explanation

▶ Debugging, configuration, ...

- ▶ Find a least resource-consuming schedule
 - Scheduling, logistics, ...
- ▶ Find a most probable explanation (MAP)
 - ▶ Probabilistic inference, ...

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High demand for automated approaches to finding good solutions to computationally hard optimization problems \rightsquigarrow Maximum satisfiability

MaxSat Applications

Drastically increasing number of successful applications

- ▶ Planning, Scheduling, and Configuration
- ▶ Data Analysis and Machine Learning
- ▶ Knowledge Representation and Reasoning
- Combinatorial Optimization
- Verification and Security
- Bioinformatics

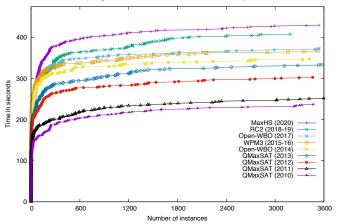
► ...

▶ Tens of new problem domains in MaxSAT Evaluations

This progress is much due to significant progress in efficient MaxSAT solvers.

Progress in MaxSat Solver Performance

Unweighted MaxSAT: Number x of instances solved in y seconds



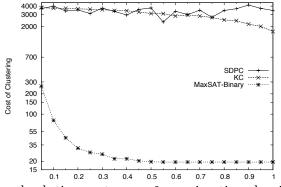
Comparing some of the best solvers from 2010–2020: In 2020: 81% more instances solved than in 2010!

On same computer, same set of benchmarks:
 576 unweighted MaxSat Evaluation 2020 instances

Benefits of (IHS-based) MaxSat

Provably optimal solutions

Example: Correlation clustering by (IHS-based) MaxSat [Berg and Järvisalo, 2017]



Improved solution costs over & pproximative algorithms
 Good performance even on sparse data (missing values)

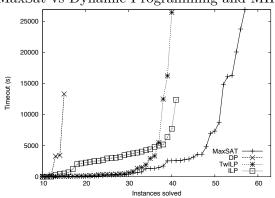
Benefits of (IHS-based) MaxSat

Surpassing the efficiency of specialized algorithms

Example:

Learning optimal bounded-treewidth Bayesian networks

[Berg, Järvisalo, and Malone, 2014]



MaxSat vs Dynamic Programming and MIP

Basic Concepts

MaxSat: Basic Definitions

 Simple constraint language: conjunctive normal form (CNF) propositional formulas

- More high-level constraints encoded as sets of clauses
- ▶ Literal: a boolean variable x or $\neg x$.
- ▶ Clause C: a disjunction (\lor) of literals. e.g (x \lor y \lor \neg z)
- Truth assignment τ : a function from Boolean variables to $\{0, 1\}$.
- ► Satisfaction:

$$\tau(\mathbf{C}) = 1$$
 if
 $\tau(\mathbf{x}) = 1$ for some literal $\mathbf{x} \in \mathbf{C}$, or
 $\tau(\mathbf{x}) = 0$ for some literal $\neg \mathbf{x} \in \mathbf{C}$.

At least one literal of C is made true by τ .

MaxSat: Basic Definitions

MaxSat
INPUT: a set of clauses F. (a CNF formula)
TASK: find
$$\tau$$
 s.t. $\sum_{C \in F} \tau(C)$ is maximized.

Find truth assignment that satisfies a maximum number of clauses

This is the standard definition, much studied in Theoretical Computer Science.

▶ Often inconvenient for modelling practical problems.

Central Generalizations of MaxSat

Weighted MaxSat

- $\blacktriangleright\,$ Each clause C has an associated weight $w_{\rm C}$
- ▶ Optimal solutions maximize the sum of weights of satisfied clauses: τ s.t. ∑_{C∈F} w_cτ(C) is maximized.

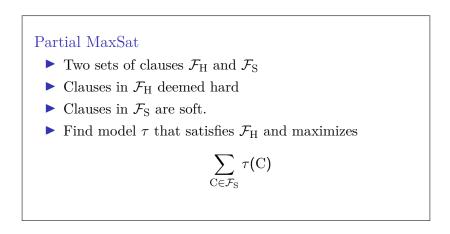
Partial MaxSat

- ▶ Two sets of clauses \mathcal{F}_{H} and \mathcal{F}_{S}
- ▶ Clauses in \mathcal{F}_{H} deemed hard
 - Any solution has to satisfy the hard clauses
- ▶ Clauses in \mathcal{F}_{S} are soft.

Weighted Partial MaxSat

Hard clauses (partial) + weights on soft clauses (weighted)

Central Generalizations of MaxSat



Rest of the talk unweighted examples All techniques applicable in the weighted case as well.

MaxSat Algorithmically

In theory - a maximization problem Find model τ that satisfies \mathcal{F}_{H} and maximizes

 $\sum_{C\in \mathcal{F}_S} \tau(C)$

MaxSat Algorithmically

In theory - a maximization problem Find model τ that satisfies \mathcal{F}_{H} and maximizes

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In practice - a minimization problem Find model τ that satisfies \mathcal{F}_{H} and minimizes $\operatorname{cost}(\tau) = \sum_{\mathrm{C}\in\mathcal{F}_{\mathrm{S}}} (1 - \tau(\mathrm{C}))$

INPUT: Instance $\mathcal{I} = (\mathcal{F}_{H}, \mathcal{F}_{S})$ OUTPUT: Solution τ that: (i) satisfies \mathcal{F}_{H} (ii) minimizes $cost(\tau) = \sum_{C \in \mathcal{F}_{S}} 1 - \tau(C)$

$$\begin{split} \mathcal{F}_{H} &= \{ (b_1 \vee b_2), (b_2 \vee b_3) \} \\ \mathcal{F}_{S} &= \{ (\neg b_1), (\neg b_2), (\neg b_3) \} \end{split}$$

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$$\tau(\mathbf{b}_1) = \tau(\mathbf{b}_3) = \tau(\mathbf{b}_2) = 1$$

 $\cot(\tau) = 3$

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$$\begin{aligned} \tau(\mathbf{b}_1) &= \tau(\mathbf{b}_3) = 0\\ \tau(\mathbf{b}_2) &= 1 \end{aligned}$$

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$$\tau = \{\neg b_1, b_2, \neg b_3\}$$

Assignments treated as sets of literals.

MaxSat: Complexity

Deciding whether k clauses can be satisfied: NP-complete Input: A CNF formula F, a positive integer k. Question:

Is there an assignment that satisfies at least k clauses in F?

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MaxSat is FP^{NP} -complete

- Polynomial number of oracle calls
- ▶ A SAT solver acts as the NP oracle most often in practice

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Complexity of IHS for solving MaxSat

Theorem

For every $n \in \mathbb{N}$ there exists an instance \mathcal{I} on which an IHS algorithm needs to perform $\Omega(2^n)$ SAT-solver calls.

A (short) overview of MaxSat solvers

Types of MaxSat Solvers

MaxSat Solver

Practical implementation of an algorithm for finding (optimal) solutions to MaxSAT instances

Focus here: Complete MaxSat solving

 Guaranteed to output a provably optimal solution to any instance

(given enough resources (time & space))

Push-Button Solvers

- Black-box, no command line parameters necessary
 mancoosi-test-i2000d0u98-26.wcnf
 p wcnf 18169 112632 31540812410
 31540812410 -1 2 3 0
- Input: CNF formula, in the standard 31540812410 -4 2 3 0 DIMACS WCNF file format
- Output: provably optimal solution, or UNSATISFIABLE
- 31540812410 -5 6 0 ... 18170 1133 0 18170 457 0 ... truncated 2 4 MB

- Complete solvers
- Internally rely especially on CDCL SAT solvers for proving unsatisfiability of subsets of clauses

Availability

Open Source

Starting from 2017, solvers need to be open-source in order to participate in MaxSat Evaluations

- ▶ Incentive for openness
- Allow other to build on and test new ideas on establish solver source bases

https://maxsat-evaluations.github.io/

Types of Complete Solvers

Branch and Bound

 Can be effective of small-but hard & randomly generated instances Types of Complete Solvers

Branch and Bound

► SAT-based MaxSat algorithms

Types of Complete Solvers

Branch and Bound

SAT-based MaxSat algorithms Model-improving

Upper Bounding

use a SAT-solver to extract solutions of increasing quality until no better ones can be found

Types of Complete Solvers

Branch and Bound

▶ SAT-based MaxSat algorithms

- Model-improving
- Core-guided

Lower Bounding

use a SAT solver to extract small sets of unsatisfiable constraints and relax the instance in a controlled way. Types of Complete Solvers

Branch and Bound

▶ SAT-based MaxSat algorithms

- Model-improving
- ► Core-guided
- Implicit hitting set

Hybrid

decouple MaxSAT solving into core-extraction and optimisation

Implicit Hitting Set Algorithms for MaxSat

[Davies and Bacchus, 2011, 2013b,a]

Goals for this Section

► Basic concepts:

► Cores

Hitting Sets

▶ Implicit Hitting set for solving MaxSAT (the simple way)

► Central in IHS MaxSAT:

$$\begin{split} \mathcal{F}_{H} &= \{(b_1 \lor b_2), (b_2 \lor b_3)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3)\} \end{split}$$

- ▶ Central in IHS MaxSAT:
- $\kappa \subset \mathcal{F}_{S}$ is an core if $\mathcal{F}_{H} \wedge \kappa$ is unsatisfiable

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- ▶ Central in IHS MaxSAT:
- $\kappa \subset \mathcal{F}_{S}$ is an core if $\mathcal{F}_{H} \wedge \kappa$ is unsatisfiable
- $\kappa \subset \mathcal{F}_{S}$ is an MUS if no $\kappa_{s} \subsetneq \kappa$ is a core.

$$\begin{split} \mathcal{F}_{H} &= \{(b_1 \lor b_2), (b_2 \lor b_3)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3)\} \end{split}$$

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► Central in IHS MaxSAT:

- $\kappa \subset \mathcal{F}_{S}$ is an core if $\mathcal{F}_{H} \wedge \kappa$ is unsatisfiable
- $\kappa \subset \mathcal{F}_{S}$ is an MUS if no $\kappa_{s} \subsetneq \kappa$ is a core.

In the rest of the presentation, we represent clauses $(b_1 \vee b_2)$ as (b_1, b_2) .

$$\begin{split} \mathcal{F}_{H} &= \{ (b_1, b_2), (b_2, b_3) \} \\ \mathcal{F}_{S} &= \{ (\neg b_1), (\neg b_2), (\neg b_3) \} \end{split}$$

$$\kappa = \{ (\neg \mathbf{b}_1), (\neg \mathbf{b}_2) \}$$

 C - a collection of cores
$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3})\} \\ \mathcal{F}_{S} &= \{(\neg b_{1}), (\neg b_{2}), (\neg b_{3})\} \end{split}$$

$$C = \{\{(\neg b_1), (\neg b_2)\}, \\ \{(\neg b_2), (\neg b_3)\}\}$$

- C a collection of cores
- ▶ hs ⊂ \mathcal{F}_{S} is an hitting set if hs ∩ $\kappa \neq \emptyset$ for all $\kappa \in C$

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$$hs_1 = \{ (\neg b_1), (\neg b_3) \}$$

$$cost(hs_1) = 2$$

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$$hs_1 = \{(\neg b_1), (\neg b_3)\}\$$

 $cost(hs_1) = 2$

 $hs_2 = \{(\neg b_2)\}$ $cost(hs_2) = 1$

- C a collection of cores
- ▶ hs ⊂ \mathcal{F}_{S} is an hitting set if hs ∩ $\kappa \neq \emptyset$ for all $\kappa \in C$
- cost(hs) = |hs| (i.e. number of clauses in it)
- ► hs is minimum-cost if no other hs' has cost(hs') < cost(hs)</p>

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3})\} \\ \mathcal{F}_{S} &= \{(\neg b_{1}), (\neg b_{2}), (\neg b_{3})\} \end{split}$$

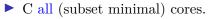
$$C = \{\{(\neg b_1), (\neg b_2)\}, \\ \{(\neg b_2), (\neg b_3)\}\}$$

1

$$hs_1 = \{(\neg b_1), (\neg b_3)\}\$$

 $cost(hs_1) = 2$

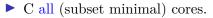
 $hs_2 = \{(\neg b_2)\}$ $cost(hs_2) = 1$



▶ hs, minimum-cost over C

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3)\} \end{split}$$

 $C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}\}$ hs = $\{(\neg b_2)\}$ cost(hs₂) = 1

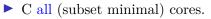


▶ → exists τ^{hs} that satisfies exactly $\mathcal{F}_{\text{H}} \land (\mathcal{F}_{\text{S}} \setminus \text{hs})$.

$$\begin{split} \mathcal{F}_{H} &= \{ (\mathbf{b_{1}}, \mathbf{b_{2}}), (\mathbf{b_{2}}, \mathbf{b_{3}}) \} \\ \mathcal{F}_{S} &= \{ (\neg \mathbf{b_{1}}), (\neg \mathbf{b_{2}}), (\neg \mathbf{b_{3}}) \} \end{split}$$

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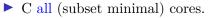
hs = $\{(\neg b_2)\}$ cost(hs₂) = 1
 $\tau^{hs} = \{\neg b_1, b_2, \neg b_3\}$ cost(τ^{hs}) = 1



- ▶ hs, minimum-cost over C
- ▶ → exists τ^{hs} that satisfies exactly $\mathcal{F}_{\text{H}} \land (\mathcal{F}_{\text{S}} \setminus \text{hs})$.

Key insight

Such hs can be computed implicitly.

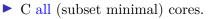


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Key insight

Such hs can be computed implicitly.

Compute a minimum-cost hs over any set of cores



- ▶ hs, minimum-cost over C
- ▶ → exists τ^{hs} that satisfies exactly $\mathcal{F}_{\text{H}} \land (\mathcal{F}_{\text{S}} \setminus \text{hs})$.

Key insight

- Such hs can be computed implicitly.
 - Compute a minimum-cost hs over any set of cores
 - Check if $\mathcal{F}_{\mathrm{H}} \wedge (\mathcal{F}_{\mathrm{S}} \setminus \mathrm{hs})$ is satisfiable.

Iterate over the following steps:

• Accumulate a collection \mathcal{K} of UNSAT cores

```
using a SAT solver
```

▶ Find an optimal hitting set hs over K, and rule out the clauses in hs for the next SAT solver call using an IP solver

... until the SAT solver returns satisfying assignment.

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• Accumulate a collection \mathcal{K} of UNSAT cores

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Hitting Set Problem as Integer Programming

$$\begin{split} \min \sum_{C \in \cup \mathcal{K}} w(C) \cdot b_C \\ \text{subject to} \quad \sum_{C \in K} b_C \quad \geq 1 \quad \forall K \in \mathcal{K} \end{split}$$

▶ $b_C = 1$ iff clause C in the hitting set

▶ Weight function w: works also for weighted MaxSat

"Best out of both worlds"

Combining the main strengths of SAT and IP solvers:

"Best out of both worlds"

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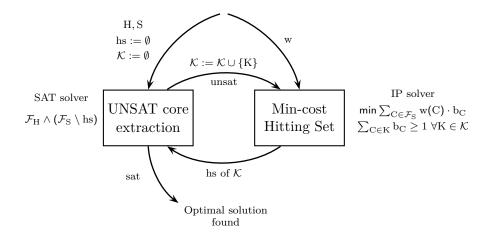
- ▶ SAT solvers are very good at proving unsatisfiability
 - Explanations for unsatisfiability in terms of cores
 - Each SAT solver call made on a subset of the clauses in the instance

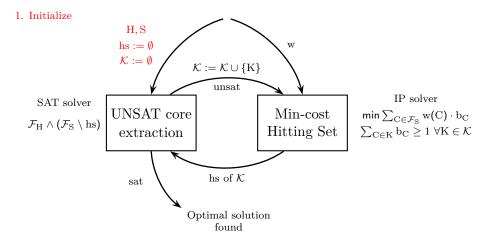
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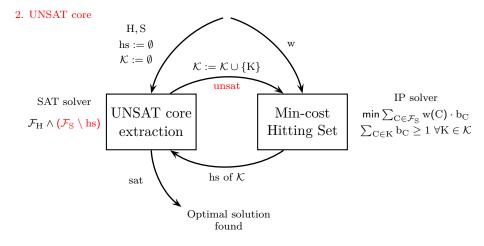
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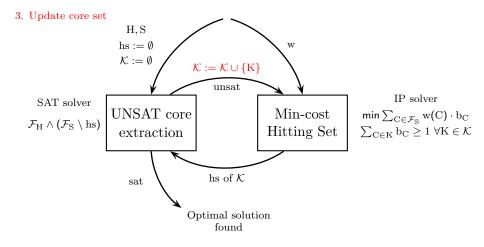
- ▶ SAT solvers are very good at proving unsatisfiability
 - Explanations for unsatisfiability in terms of cores
 - Each SAT solver call made on a subset of the clauses in the instance
- ▶ IP solvers at optimization
 - ▶ Instead of directly solving the input MaxSAT instance: solve a sequence of simpler hitting set problems over the cores

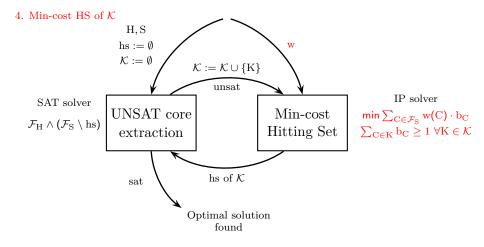
Input:

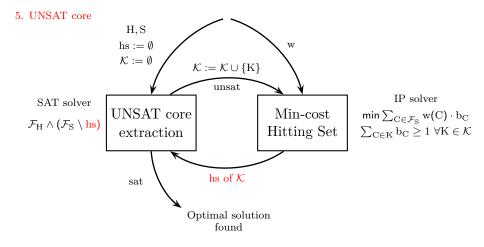


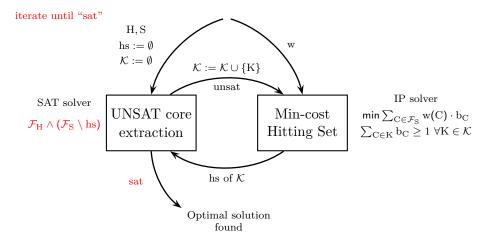


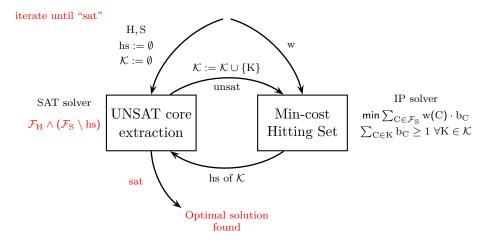




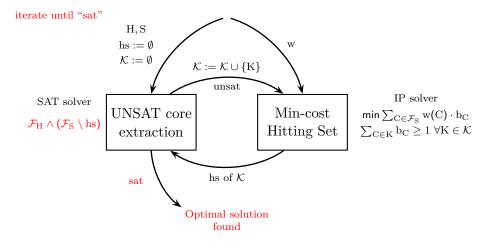






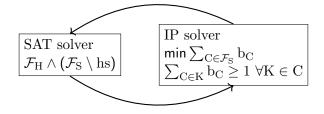


Intuition: After optimally hitting all cores of $\mathcal{F}_{H} \wedge \mathcal{F}_{S}$ by hs: any solution to $\mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs)$ is guaranteed to be optimal.



$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$

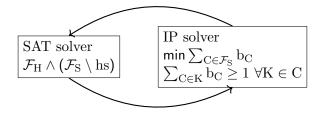
Basic-IHS
$$(\mathcal{F})$$



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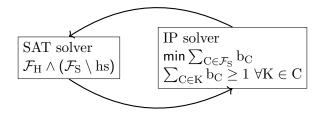
Initialize



$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$

Basic-IHS (\mathcal{F})

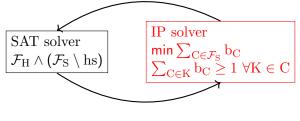
Initialize while True



$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$

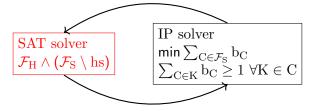
Basic-IHS (\mathcal{F})

Initialize while True Compute hs



ip-solve $hs = \emptyset$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$

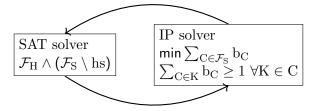


Basic-IHS (\mathcal{F})

 $\begin{array}{l} \mbox{Initialize} \\ \mbox{while True} \\ \mbox{Compute hs} \\ \mbox{SAT-solve } \mathcal{F}_{\rm H} \wedge (\mathcal{F}_{\rm S} \setminus {\rm hs}) \end{array}$

 $\begin{array}{l} \mathrm{sat-solve} \\ \mathcal{F}_H \wedge \{ (\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4) \} \qquad \mathrm{hs} = \emptyset \end{array}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



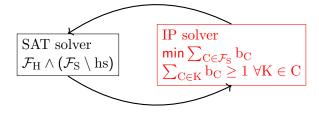
Basic-IHS (\mathcal{F})

 $\begin{array}{l} \mbox{Initialize} \\ \mbox{while True} \\ \mbox{Compute hs} \\ \mbox{SAT-solve } \mathcal{F}_{\rm H} \wedge (\mathcal{F}_{\rm S} \setminus {\rm hs}) \\ \mbox{If UNSAT} \\ \mbox{add core to C} \end{array}$

 $sat-solve \\ \mathcal{F}_H \wedge \{ (\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4) \}$

Result UNSAT $\kappa = \{(\neg b_1), (\neg b_2)\}$ C = $\{\{(\neg b_1), (\neg b_2)\}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



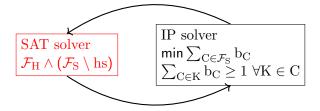
Basic-IHS (\mathcal{F})

 $\begin{array}{ll} \mbox{Initialize} & & \\ \mbox{while True} & & \\ \mbox{Compute hs} & & \\ \mbox{SAT-solve } \mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs) & \\ \mbox{If UNSAT} & & \\ \mbox{add core to C} & & \\ \end{array}$

 $\begin{array}{l} \mathrm{ip}\mathrm{-solve} \\ \mathrm{hs} = \{(\neg \mathrm{b}_1)\} \end{array}$

 $C = \{\{(\neg b_1), (\neg b_2)\}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



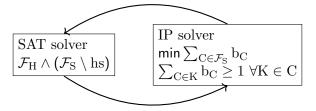
Basic-IHS
$$(\mathcal{F})$$

Initialize while True Compute hs SAT-solve $\mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs)$ If UNSAT add core to C

 $\begin{array}{ll} \mathrm{sat-solve} \\ \mathcal{F}_H \wedge \{(\neg b_2), (\neg b_3), (\neg b_4)\} \end{array} \qquad \qquad \mathrm{hs} = \{(\neg b_1)\} \end{array}$

 $C = \{\{(\neg b_1), (\neg b_2)\}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



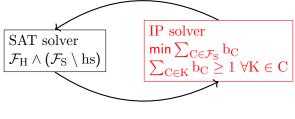
Basic-IHS (\mathcal{F})

 $\begin{array}{l} \mbox{Initialize} \\ \mbox{while True} \\ \mbox{Compute hs} \\ \mbox{SAT-solve } \mathcal{F}_{\rm H} \wedge (\mathcal{F}_{\rm S} \setminus {\rm hs}) \\ \mbox{If UNSAT} \\ \mbox{add core to C} \end{array}$

 $\begin{array}{l} \mathrm{sat-solve} \\ \mathcal{F}_{\mathrm{H}} \wedge \{(\neg b_2), (\neg b_3), (\neg b_4)\} \end{array}$

Result UNSAT $\kappa = \{(\neg b_2), (\neg b_3)\}$ C = $\{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



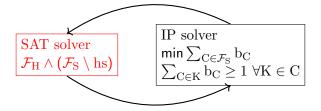
Basic-IHS
$$(\mathcal{F})$$

 $\begin{array}{ll} \mbox{Initialize} & & \\ \mbox{while True} & & \\ \mbox{Compute hs} & & \\ \mbox{SAT-solve } \mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs) & \\ \mbox{If UNSAT} & & \\ \mbox{add core to C} & & \\ \end{array}$

ip-solve $hs = \{(\neg b_2)\}$

 $C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



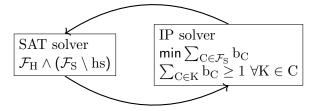
Basic-IHS
$$(\mathcal{F})$$

Initialize while True Compute hs SAT-solve $\mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs)$ If UNSAT add core to C

 $\begin{array}{ll} \mathrm{sat-solve} \\ \mathcal{F}_{\mathrm{H}} \wedge \{(\neg \mathrm{b}_1), (\neg \mathrm{b}_3), (\neg \mathrm{b}_4)\} \end{array} \qquad \qquad \mathrm{hs} = \{(\neg \mathrm{b}_2)\} \end{array}$

 $C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



Basic-IHS (\mathcal{F})

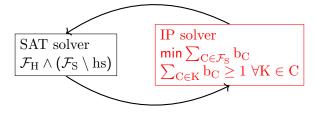
 $\begin{array}{l} \mbox{Initialize} \\ \mbox{while True} \\ \mbox{Compute hs} \\ \mbox{SAT-solve } \mathcal{F}_{\rm H} \wedge (\mathcal{F}_{\rm S} \setminus {\rm hs}) \\ \mbox{If UNSAT} \\ \mbox{add core to C} \end{array}$

 $\begin{array}{l} {\rm sat-solve} \\ \mathcal{F}_{H} \wedge \{ (\neg b_1), (\neg b_3), (\neg b_4) \} \end{array}$

Result UNSAT $\kappa = \{(\neg b_3), (\neg b_4)\}$

$$C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}, (\neg b_3), (\neg b_4)\}\}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



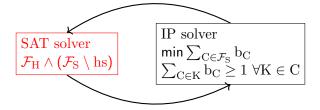
Basic-IHS
$$(\mathcal{F})$$

 $\begin{array}{ll} \mbox{Initialize} & & \\ \mbox{while True} & & \\ \mbox{Compute hs} & & \\ \mbox{SAT-solve } \mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs) & \\ \mbox{If UNSAT} & & \\ \mbox{add core to C} & & \\ \end{array}$

 $ip-solve \\ hs = \{(\neg b_2), (\neg b_3)\}$

$$C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}, \\ (\neg b_3), (\neg b_4)\}\}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$



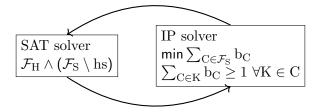
Basic-IHS
$$(\mathcal{F})$$

Initialize while True Compute hs SAT-solve $\mathcal{F}_{H} \wedge (\mathcal{F}_{S} \setminus hs)$ If UNSAT add core to C

 $\begin{array}{ll} \mathrm{sat-solve} \\ \mathcal{F}_H \wedge \{(\neg b_1), (\neg b_4)\} \end{array} \qquad \qquad \mathrm{hs} = \{(\neg b_2), (\neg b_3)\} \end{array}$

$$C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}, (\neg b_3), (\neg b_4)\}\}$$

$$\begin{split} \mathcal{F}_{H} &= \{ (b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}) \} \\ \mathcal{F}_{S} &= \{ (\neg b_{1}), (\neg b_{2}), (\neg b_{3}), (\neg b_{4}) \} \end{split}$$



Basic-IHS (\mathcal{F})

 $\begin{array}{ll} \mbox{Initialize} \\ \mbox{while True} \\ \mbox{Compute hs} \\ \mbox{SAT-solve } \mathcal{F}_{\rm H} \wedge (\mathcal{F}_{\rm S} \setminus {\rm hs}) \\ \mbox{If UNSAT} \\ \mbox{add core to C} \\ \mbox{ELSE} \\ \mbox{return } \tau \\ \end{array}$

sat-solve $\mathcal{F}_{H} \wedge \{(\neg b_1), (\neg b_4)\}$

Result SAT $\tau = \{\neg b_1, b_2, b_3, \neg b_4\}$

$$C = \{\{(\neg b_1), (\neg b_2)\}, \{(\neg b_2), (\neg b_3)\}, (\neg b_3), (\neg b_4)\}\}$$

Implicit Hitting Sets with Bounds

Goals for this Section

MaxSat in terms of blocking variables
 IHS in terms of bounds.

 Various modern CDCL SAT solvers implement an API for solving under assumptions.

$$\mathcal{F}_{H} = \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\}$$

assumps = {¬b₁, ¬b₃}

 Various modern CDCL SAT solvers implement an API for solving under assumptions.

- ▶ assumps: a set of literals
- sat-assume(\mathcal{F} , assumps) returns either:

$$\mathcal{F}_{H} = \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\}$$

assumps = $\{\neg b_1, \neg b_3\}$

- Various modern CDCL SAT solvers implement an API for solving under assumptions.
 - ▶ assumps: a set of literals
 - ▶ sat-assume(\mathcal{F} , assumps) returns either:
 - a solution τ , that satisfies \mathcal{F} and sets $\tau(l) = 1$ for all $l \in assumps$.

$$\begin{aligned} \mathcal{F}_{H} &= \{ (b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}) \} \\ assumps &= \{ \neg b_{1}, \neg b_{3} \} \end{aligned}$$

sat-assume
$$(\mathcal{F}_{H}, assumps) = SAT$$

 $\tau = \{\neg b_1, b_2, \neg b_3, b_4\}$

- Various modern CDCL SAT solvers implement an API for solving under assumptions.
 - ▶ assumps: a set of literals
 - ▶ sat-assume(\mathcal{F} , assumps) returns either:
 - a solution τ , that satisfies \mathcal{F} and sets $\tau(l) = 1$ for all $l \in assumps$.

$$\mathcal{F}_{H} = \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\}$$

assumps = $\{\neg b_1, \neg b_2, \neg b_3\}$

- Various modern CDCL SAT solvers implement an API for solving under assumptions.
 - ▶ assumps: a set of literals
 - ▶ sat-assume(\mathcal{F} , assumps) returns either:
 - a solution τ , that satisfies \mathcal{F} and sets $\tau(l) = 1$ for all $l \in assumps$.
 - unsat if no such solution exists.

$$\mathcal{F}_{H} = \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\}$$

assumps = { $\neg b_{1}, \neg b_{2}, \neg b_{3}\}$

 $\operatorname{sat-assume}(\mathcal{F}_{\mathrm{H}}, \operatorname{assumps}) = \operatorname{UNSAT}$

- Various modern CDCL SAT solvers implement an API for solving under assumptions partial assignments.
 - ▶ assumps: <u>a set of literals a partial assignment</u>
 - ▶ sat-assume(\mathcal{F} , assumps) returns either:
 - τ , an extension of assumpt that satisfies \mathcal{F}
 - unsat if no such solution exists.

$$\mathcal{F}_{H} = \{ (b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}) \}$$

assumps = {\ge b_{1}, \ge b_{2}, \ge b_{3} }

 $\operatorname{sat-assume}(\mathcal{F}_{H}, \operatorname{assumps}) = \operatorname{UNSAT}$

What does this have to do with MaxSAT?

CDCL SAT solvers determine unsatisfiability when learning the empty clause

► By propagating a conflict at decision level 0

What does this have to do with MaxSAT?

CDCL SAT solvers determine unsatisfiability when learning the empty clause

▶ By propagating a conflict at decision level 0

Explaining unsatisfiability under assumptions

- ▶ Trace the reason for unsatisfiability back to assumptions that were necessary for the conflict.
- ► Essentially:
 - ▶ Force the assumptions as the first "decisions"
 - ▶ When one of these decisions results in a conflict: trace the reason of the conflict back to the forced assumptions

 Instrument each soft clause C_i with a new "assumption" variable a_i

 \rightsquigarrow replace C_i with ($C_i \lor a_i)$ for each soft clause C_i

•
$$a_i = 0$$
 switches C_i "on",
 $a_i = 1$ switches C_i "off"

▶ \mathcal{F}_{S}^{E} : soft clauses extended with assumption variables

▶
$$\neg \mathcal{A} = \{\neg a_i\}$$
 negation of all assumption variables

 Instrument each soft clause C_i with a new "assumption" variable a_i

 \rightsquigarrow replace C_i with ($C_i \lor a_i$) for each soft clause C_i

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$$a_i = 0$$
 switches C_i "on",

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- \triangleright \mathcal{F}_{S}^{E} : soft clauses extended with assumption variables
- ▶ $\neg A = \{\neg a_i\}$ negation of all assumption variables

 Instrument each soft clause C_i with a new "assumption" variable a_i

 \rightsquigarrow replace C_i with ($C_i \lor a_i)$ for each soft clause C_i

- $\triangleright \mathcal{F}_{S}^{E}$: soft clauses extended with assumption variables
- ▶ $\neg \tilde{\mathcal{A}} = \{\neg a_i\}$ negation of all assumption variables
- ▶ MaxSat core: a subset of the assumptions variables

• Invoke sat-assume(
$$\mathcal{F}_{H} \land \mathcal{F}_{S}^{E}, \neg \mathcal{A}$$
)

 Instrument each soft clause C_i with a new "assumption" variable a_i

 \rightsquigarrow replace C_i with ($C_i \lor a_i$) for each soft clause C_i

•
$$a_i = 0$$
 switches C_i "on",
 $a_i = 1$ switches C_i "off"

- $\triangleright \mathcal{F}_{S}^{E}$: soft clauses extended with assumption variables
- $\neg \tilde{\mathcal{A}} = \{\neg a_i\}$ negation of all assumption variables

- Invoke sat-assume ($\mathcal{F}_{H} \wedge \mathcal{F}_{S}^{E}, \neg \mathcal{A}$)
- ▶ If UNSAT, obtain subset $\kappa_a \subset \mathcal{A}$

 Instrument each soft clause C_i with a new "assumption" variable a_i

 \rightsquigarrow replace C_i with ($C_i \lor a_i$) for each soft clause C_i

- $\triangleright \mathcal{F}_{S}^{E}$: soft clauses extended with assumption variables
- ▶ $\neg A = \{\neg a_i\}$ negation of all assumption variables

- Invoke sat-assume ($\mathcal{F}_{H} \wedge \mathcal{F}_{S}^{E}, \neg \mathcal{A}$)
- ▶ If UNSAT, obtain subset $\kappa_a \subset \mathcal{A}$
- Map to core $\kappa = \{C_i \mid a_i \in \kappa_a\}$

 Instrument each soft clause C_i with a new "assumption" variable a_i

 \rightsquigarrow replace C_i with ($C_i \lor a_i$) for each soft clause C_i

- $\triangleright \mathcal{F}_{S}^{E}$: soft clauses extended with assumption variables
- $\neg \tilde{\mathcal{A}} = \{\neg a_i\}$ negation of all assumption variables

- Invoke sat-assume ($\mathcal{F}_{H} \wedge \mathcal{F}_{S}^{E}, \neg \mathcal{A}$)
- ▶ If UNSAT, obtain subset $\kappa_a \subset \mathcal{A}$
- Map to core $\kappa = \{C_i \mid a_i \in \kappa_a\}$
- ▶ Used by all core-based MaxSAT algorithms.

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2), (\neg b_3), (\neg b_4)\} \end{split}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{S}^{E} &= \{(\neg b_{1} \lor a_{1}), (\neg b_{2} \lor a_{2}), (\neg b_{3} \lor a_{3}), (\neg b_{4} \lor a_{4})\} \end{split}$$

1. Extend Soft Clauses

$$egin{aligned} \mathcal{F}_{\mathrm{H}} &= \{(\mathrm{b}_1, \mathrm{b}_2), (\mathrm{b}_2, \mathrm{b}_3), (\mathrm{b}_3, \mathrm{b}_4)\} \ \mathcal{F}_{\mathrm{S}}^{\mathrm{E}} &= \{(\neg \mathrm{b}_1 \lor \mathrm{a}_1), (\neg \mathrm{b}_2 \lor \mathrm{a}_2), (\neg \mathrm{b}_3 \lor \mathrm{a}_3), (\neg \mathrm{b}_4 \lor \mathrm{a}_4)\} \end{aligned}$$

 $\operatorname{sat-assume}(\mathcal{F}_{H} \land \mathcal{F}_{S}^{E}, \{\neg a_{1}, \neg a_{2}, \neg a_{3}, \neg a_{4}\})$

- 1. Extend Soft Clauses
- 2. Invoke SAT-solver under assumptions

$$egin{aligned} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \ \mathcal{F}_{S}^{E} &= \{(\neg b_{1} \lor a_{1}), (\neg b_{2} \lor a_{2}), (\neg b_{3} \lor a_{3}), (\neg b_{4} \lor a_{4})\} \end{aligned}$$

 $sat-assume(\mathcal{F}_{H} \land \mathcal{F}_{S}^{E}, \{\neg a_{1}, \neg a_{2}, \neg a_{3}, \neg a_{4}\})$

Results: UNSAT

- 1. Extend Soft Clauses
- 2. Invoke SAT-solver under assumptions

$$egin{aligned} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \ \mathcal{F}^{E}_{S} &= \{(\neg b_{1} \lor a_{1}), (\neg b_{2} \lor a_{2}), (\neg b_{3} \lor a_{3}), (\neg b_{4} \lor a_{4})\} \end{aligned}$$

 $sat-assume(\mathcal{F}_{H} \land \mathcal{F}_{S}^{E}, \{\neg a_{1}, \neg a_{2}, \neg a_{3}, \neg a_{4}\})$

Results: UNSAT $\kappa_a = \{a_1, a_2\}$

- 1. Extend Soft Clauses
- 2. Invoke SAT-solver under assumptions
- 3. Obtain subset of negated assumptions

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{S}^{E} &= \{(\neg b_{1} \lor a_{1}), (\neg b_{2} \lor a_{2}), (\neg b_{3} \lor a_{3}), (\neg b_{4} \lor a_{4})\} \end{split}$$

$$\operatorname{sat-assume}(\mathcal{F}_{H} \land \mathcal{F}_{S}^{E}, \{\neg a_{1}, \neg a_{2}, \neg a_{3}, \neg a_{4}\})$$

Results: UNSAT

$$\kappa_{a} = \{a_{1}, a_{2}\} \longrightarrow \kappa = \{(\neg b_{1}), (\neg b_{2})\}$$

- 1. Extend Soft Clauses
- 2. Invoke SAT-solver under assumptions
- 3. Obtain subset of negated assumptions
- 4. Obtain core.

$$\begin{split} \mathcal{F}_{H} &= \{ (b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}) \} \\ \mathcal{F}_{S}^{E} &= \{ (\neg b_{1} \lor a_{1}), (\neg b_{2} \lor a_{2}), (\neg b_{3} \lor a_{3}), (\neg b_{4} \lor a_{4}) \} \end{split}$$

sa Observation: Unit soft clauses do not need assumption variables

Results: UNSAT

$$\kappa_{a} = \{a_{1}, a_{2}\} \longrightarrow \kappa = \{(\neg b_{1}), (\neg b_{2})\}$$

- 1. Extend Soft Clauses
- 2. Invoke SAT-solver under assumptions
- 3. Obtain subset of negated assumptions
- 4. Obtain core.

MaxSat via Blocking Variables

Clauses

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, x)(\neg x, b_2)\}\\ \mathcal{F}_{S} &= \{(\neg b_1), (\neg b_2)\} \end{split}$$

Assume all soft clauses are unit negative literals.

MaxSat via Blocking Variables

Assume all soft clauses are unit negative literals. Blocking Variable: a variable that appears in a "soft clauses"

MaxSat via Blocking Variables

Clauses $\mathcal{F}_{H} = \{(b_1, x)(\neg x, b_2)\}$ $\mathcal{F}_{S} = \{(\neg b_1), (\neg b_2)\}$

$$\begin{split} & \text{Blocking Vars.} \\ & \mathcal{F}_H = \{(b_1, x)(\neg x, b_2)\} \\ & \mathcal{F}_B = \{b_1, b_2\} \end{split}$$

Find $\tau(\mathcal{F}_{H}) = 1$ minimizing $\operatorname{cost}(\tau) = \sum_{C \in \mathcal{F}_{S}} (1 - \tau(C))$

Find
$$\tau(\mathcal{F}_{H}) = 1$$
 minimizing
 $\operatorname{cost}(\tau) = \sum_{b \in \mathcal{F}_{B}} \tau(b)$

Assign weight to blocking variables instead

MaxSat via Blocking Variables

Clauses $\mathcal{F}_{H} = \{(b_{1}, x)(\neg x, b_{2})\}$ $\mathcal{F}_{S} = \{(\neg b_{1}), (\neg b_{2})\}$ Find $\tau(\mathcal{F}_{H}) = 1$ minimizing $\cot(\tau) = \sum_{C \in \mathcal{F}_{S}} (1 - \tau(C))$ $\kappa = \{(\neg b_{1}), (\neg b_{2})\} \subset \mathcal{F}_{S}$ $\mathcal{F}_{H} \land (\neg b_{1}) \land (\neg b_{2})$ UNSAT

$$\begin{split} & \text{Blocking Vars.} \\ & \mathcal{F}_H = \{(b_1, x)(\neg x, b_2)\} \\ & \mathcal{F}_B = \{b_1, b_2\} \end{split}$$

Find $\tau(\mathcal{F}_{H}) = 1$ minimizing $\operatorname{cost}(\tau) = \sum_{b \in \mathcal{F}_{B}} \tau(b)$

 $\begin{aligned} \kappa &= (b_1, b_2) \\ \mathcal{F}_H &\models (b_1, b_2) \end{aligned}$

Core: a clause over (set of) blocking variables entailed by \mathcal{F}_{H} .

MaxSat via Blocking Variables

ClausesBlocking Vars. $\mathcal{F}_{H} = \{(b_1, x)(\neg x, b_2)\}$ $\mathcal{F}_{H} = \{(b_1, x)(\neg x, b_2)\}$ $\mathcal{F}_{S} = \{(\neg b_1), (\neg b_2)\}$ $\mathcal{F}_{B} = \{b_1, b_2\}$ Find $\tau(\mathcal{F}_{H}) = 1$ minimizing
 $cost(\tau) = \sum_{C \in \mathcal{F}_{S}} (1 - \tau(C))$ Find $\tau(\mathcal{F}_{H}) = 1$ minimizing
 $cost(\tau) = \sum_{b \in \mathcal{F}_{B}} \tau(b)$ $\kappa = \{(\neg b_1), (\neg b_2)\} \subset \mathcal{F}_{S}$ $\kappa = (b_1, b_2)$ $\mathcal{F}_{H} \land (\neg b_1) \land (\neg b_2)$ UNSAT $\mathcal{F}_{H} \models (b_1, b_2)$

Core: a clause over (set of) blocking variables entailed by \mathcal{F}_{H} . Hitting Set: a subset of blocking variables with non-empty intersection with cores. Core Extraction with Blocking Variables

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{split}$$

sat-assume($\mathcal{F}_{H}, \{\neg b \mid b \in \mathcal{F}_{B}\}$) Results: UNSAT $\kappa = \{b_1, b_2\}$

1. Core extraction

Core Extraction with Blocking Variables

$$\begin{aligned} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{aligned}$$

$$C = \{(b_1, b_2), (b_2, b_3)\} \qquad hs = \{b_2\}$$

sat-assume($\mathcal{F}_H, \{\neg b \mid b \in \mathcal{F}_B \setminus hs\}$)
Results: UNSAT
 $\kappa = \{b_3, b_4\}$

2. Hitting set test:

Upper bounds from Core Extraction

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- ► A new hitting set is not needed after every core.
- ▶ Instead, keep extracting cores until solver reports SAT

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Lower bounds from hitting sets

Proposition:

Let C be any set of cores and hs a minimum-cost hitting set. Then |hs| is a lower bound on the optimal cost.

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Lower bounds from hitting sets

Proposition:

Let C be any set of cores and hs a minimum-cost hitting set. Then |hs| is a lower bound on the optimal cost.

i.e. sizes of minimum-cost hitting sets over cores provide lower bounds.

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4})\}\\ \mathcal{F}_{B} &= \{b_{1},b_{2},b_{3},b_{4}\} \end{split}$$

Basic-IHS
$$(\mathcal{F})$$

Basic-IHS (\mathcal{F})

Initialize

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{split}$$

 $UB = \infty$ LB = 0 $C = \emptyset$ $bestsol = \emptyset$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\}\\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{split}$$

Basic-IHS (\mathcal{F})

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hs = Min-Hs $(\mathcal{F}_{\mathrm{B}}, \emptyset)$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs

 $UB = \infty$ LB = 0 $C = \emptyset$ $bestsol = \emptyset$

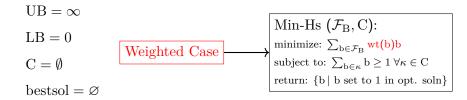
$$\begin{split} & \text{Min-Hs } \left(\mathcal{F}_{\mathrm{B}}, \mathrm{C}\right): \\ & \text{minimize: } \sum_{\mathrm{b} \in \mathcal{F}_{\mathrm{B}}} \mathrm{b} \\ & \text{subject to: } \sum_{\mathrm{b} \in \kappa} \mathrm{b} \geq 1 \ \forall \kappa \in \mathrm{C} \\ & \text{return: } \{\mathrm{b} \mid \mathrm{b} \text{ set to } 1 \text{ in opt. soln} \} \end{split}$$

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Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs



$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{split}$$

 $hs = \emptyset$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB

 $UB = \infty$ $LB = |\emptyset|$ $C = \emptyset$ $bestsol = \emptyset$

$$\begin{split} \text{Min-Hs} & (\mathcal{F}_B, \mathbf{C}):\\ \text{minimize: } \sum_{\mathbf{b} \in \mathcal{F}_B} \mathbf{b}\\ \text{subject to: } \sum_{\mathbf{b} \in \kappa} \mathbf{b} \geq 1 \ \forall \kappa \in \mathbf{C}\\ \text{return: } \{\mathbf{b} \mid \mathbf{b} \text{ set to } 1 \text{ in opt. soln} \} \end{split}$$

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 $\begin{aligned} \mathbf{hs} &= \emptyset \\ \mathcal{A} &= \mathcal{F}_{\mathrm{B}} \setminus \mathbf{hs} \end{aligned}$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions

 $UB = \infty$ LB = 0 $C = \emptyset$ $bestsol = \emptyset$

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sat-assume($\mathcal{F}_H, \neg \mathcal{A}$) $\mathcal{A} = \{b_1, b_2, b_3, b_4\}$ $K = \{\}$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT

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$$\begin{split} \text{Min-Hs} \ & (\mathcal{F}_{\mathrm{B}}, \mathrm{C}): \\ \text{minimize: } \sum_{\mathrm{b} \in \mathcal{F}_{\mathrm{B}}} \mathrm{b} \\ \text{subject to: } \sum_{\mathrm{b} \in \kappa} \mathrm{b} \geq 1 \ \forall \kappa \in \mathrm{C} \\ \text{return: } \{\mathrm{b} \mid \mathrm{b} \text{ set to } 1 \text{ in opt. soln} \} \end{split}$$

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sat-assume($\mathcal{F}_{H}, \neg \mathcal{A}$) $\mathcal{A} = \{ \mathbf{b}_{1}, \mathbf{b}_{2}, \mathbf{b}_{3}, \mathbf{b}_{4} \}$ $K = \{ (\mathbf{b}_{1}, \mathbf{b}_{2}) \}$ Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT

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$$\begin{split} & \text{Min-Hs } \left(\mathcal{F}_{B}, C\right): \\ & \text{minimize: } \sum_{b \in \mathcal{F}_{B}} b \\ & \text{subject to: } \sum_{b \in \kappa} b \geq 1 \ \forall \kappa \in C \\ & \text{return: } \{b \mid b \text{ set to 1 in opt. soln} \} \end{split}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\} \\ \mathcal{F}_{B} &= \{b_1, b_2, b_3, b_4\} \end{split}$$

$$\begin{split} \mathrm{sat-assume}(\mathcal{F}_H,\neg\mathcal{A})\\ \mathcal{A} &= \{b_3,b_4\}\\ \mathrm{K} &= \{(b_1,b_2)\} \end{split}$$

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Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT

 $UB = \infty$ LB = 0 $C = \emptyset$ $bestsol = \emptyset$

 $\begin{array}{l} \text{Min-Hs } (\mathcal{F}_{B}, C) \text{:} \\ \text{minimize: } \sum_{b \in \mathcal{F}_{B}} b \\ \text{subject to: } \sum_{b \in \kappa} b \geq 1 \ \forall \kappa \in C \\ \text{return: } \{b \mid b \text{ set to } 1 \text{ in opt. soln} \} \end{array}$

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$$\begin{split} & \mathrm{sat}\text{-assume}(\mathcal{F}_H,\neg\mathcal{A})\\ & \mathcal{A}=\{\}\\ & \mathrm{K}=\{(b_1,b_2),(b_3,b_4)\} \end{split}$$

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Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT

 $UB = \infty$ LB = 0 $C = \emptyset$ $bestsol = \emptyset$

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sat-assume($\mathcal{F}_{H}, \neg \mathcal{A}$) $\mathcal{A} = \{\}$ $K = \{(b_1, b_2), (b_3, b_4)\}$ $\tau = \{\neg b_1, b_2, \neg b_3, b_4\}$

 $UB = \infty$ LB = 0 $C = \emptyset$

 $bestsol = \emptyset$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT

 $\begin{array}{l} \text{Min-Hs} \ (\mathcal{F}_{\mathrm{B}}, \mathrm{C}): \\ \text{minimize: } \sum_{\mathrm{b} \in \mathcal{F}_{\mathrm{B}}} \mathrm{b} \\ \text{subject to: } \sum_{\mathrm{b} \in \kappa} \mathrm{b} \geq 1 \ \forall \kappa \in \mathrm{C} \\ \text{return: } \{\mathrm{b} \mid \mathrm{b} \text{ set to } 1 \text{ in opt. soln} \} \end{array}$

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$$K = \{(b_1, b_2), (b_3, b_4)\}$$

$$\tau = \{\neg b_1, b_2, \neg b_3, b_4\}$$

 $\mathrm{UB} = \mathrm{cost}(\tau)$

LB = 0

 $\mathbf{C}=\emptyset$

 $bestsol = \{\neg b_1, b_2, \neg b_3, b_4\}$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB

Min-Hs (\mathcal{F}_{B}, C): minimize: $\sum_{b \in \mathcal{F}_{B}} b$ subject to: $\sum_{b \in \kappa} b \ge 1 \ \forall \kappa \in C$ return: {b| b set to 1 in opt. soln}

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{split}$$

$$K = \{ (b_1, b_2), (b_3, b_4) \}$$

$$\tau = \{ \neg b_1, b_2, \neg b_3, b_4 \}$$

UB = 2

LB = 0

 $C = \{(b_1, b_2), (b_3, b_4)\}$ bestsol = {¬b₁, b₂, ¬b₃, b₄}

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

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Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

UB = 2 LB = 0 $C = \{(b_1, b_2), (b_3, b_4)\}$ $bestsol = \{\neg b_1, b_2, \neg b_3, b_4\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} \end{split}$$

 $hs = Min-Hs (\mathcal{F}_B, \{(b_1, b_2), (b_3, b_4)\})$

$$\begin{split} UB &= 2 \\ LB &= 0 \\ C &= \{ (b_1, b_2), (b_3, b_4) \} \\ bestsol &= \{ \neg b_1, b_2, \neg b_3, b_4 \} \end{split}$$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

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 $hs=\{b_1,b_4\}$

UB = 2 $LB = |\{b_1, b_4\}|$ $C = \{(b_1, b_2), (b_3, b_4)\}$ $bestsol = \{\neg b_1, b_2, \neg b_3, b_4\}$ Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

$$\mathcal{F}_{H} = \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\}$$
$$\mathcal{F}_{B} = \{b_{1}, b_{2}, b_{3}, b_{4}\}$$
$$hs = \{b_{1}, b_{4}\}$$
$$UB = 2$$
$$LB = 2$$
$$C = \{(b_{1}, b_{2}), (b_{3}, b_{4})\}$$
$$bestsol = \{\neg b_{1}, b_{2}, \neg b_{3}, b_{4}\}$$

Basic-IHS (\mathcal{F})

Initialize while LB < UB Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C return bestsol

$$\begin{aligned} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4})\} & \text{Basic-IHS } (\mathcal{F}) \\ \mathcal{F}_{B} &= \{b_{1}, b_{2}, b_{3}, b_{4}\} & \text{Initialize} \\ \text{hs} &= \{b_{1}, b_{4}\} & \text{Compute min-cost hitting set hs} \\ \text{Update LB} & \text{Set up assumptions} \\ \text{Extract cores until SAT} \\ \text{Update UB} \\ \text{Add cores to C} \\ \text{return bestsol} \end{aligned}$$

 $LB = 2 \xleftarrow{LB need to be increased}$ $LB = 2 \xleftarrow{LB need to be increased}$ $to optimum before termination}$ $C = {(b_1, b_2), (b_3, b_4)}$ $bestsol = {\neg b_1, b_2, \neg b_3, b_4}$

Optimizations in Solvers

...

Solvers implementing the implicit hittings set approach include several optimizations, such as

- a non-optimal hitting sets for extracting several cores before/between hitting set computations, [Davies and Bacchus, 2011, 2013b,a; Saikko, Berg, and Järvisalo, 2016a]
- LP-solving techniques such as reduced cost fixing in the hitting sets

[Bacchus, Hyttinen, Järvisalo, and Saikko, 2017]

Some of these optimizations are integral for making the solvers competitive.

Implicit Hitting Sets

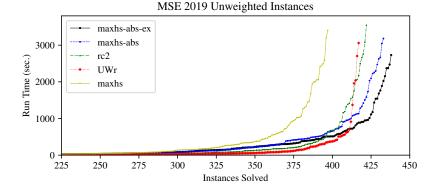
- ▶ Effective on range of MaxSat problems including large ones.
- Superior to other methods when there are many distinct weights.
- ▶ Usually superior to CPLEX for solving MaxSAT instances.

Abstract Cores

Goals for this section

- 1. What are the weaknesses of IHS for MaxSAT?
- 2. What are abstract cores and how do they address the weaknesses?
- 3. How can abstract core reasoning be incorporated into IHS?
- 4. What effect does it have?

Goals for this section



Goals for this section



MSE 2019 Unweighted Instances

Drawbacks of IHS Davies [2013]

Main motivation for abstract cores: There exists MaxSAT instances on which IHS needs an exponential number of cores.

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$$\begin{split} \mathcal{F}_{H} &= \left\{ \mathrm{CNF}(\sum_{i=1}^{n} b_{i} \geq r) \right\} \\ \mathcal{F}_{B} &= \{b_{1}, \ldots, b_{n}\} \end{split}$$

Any solution assigns r b-vars to $1 \Rightarrow$ any subset of b-vars with at least (n - r) + 1 elements has one set to 1

Main motivation for abstract cores: There exists MaxSAT instances on which IHS needs an exponential number of cores.

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$$\begin{split} n &= 8, \quad r = 4 \\ \kappa_1 &= \left(b_{i_1}, b_{i_2}, b_{i_3}, b_{i_4}, b_{i_5} \right) \\ \text{is a core for any } i_1, i_2, i_3, i_4, i_5 \end{split}$$

Intuition:

Any $\kappa \subset \mathcal{F}_B$ s.t $|\kappa| = (n - r) + 1$ is a core.

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 $\kappa_2 = (b_{i_1}, b_{i_2}, b_{i_3}, b_{i_4})$ is not a core for any i_1, i_2, i_3, i_4

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Any $\kappa \subset \mathcal{F}_B$ s.t $|\kappa| = (n - r) + 1$ is a core. IHS needs to extract all $\binom{n}{(n-r)+1}$ of them.

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n = 8, r = 4 $\kappa_1 = (b_{i_1}, b_{i_2}, b_{i_3}, b_{i_4}, b_{i_5})$ $\mathcal{F}_{\mathrm{H}} = \left\{ \mathrm{CNF}(\sum_{i=1}^{n} \mathrm{b}_{i} \geq \mathrm{r}) \right\}$ is a core for any i_1, i_2, i_3, i_4, i_5 $\mathcal{F}_{\mathrm{B}} = \{\mathbf{b}_1, \ldots, \mathbf{b}_n\}$ $\kappa_2 = (b_{i_1}, b_{i_2}, b_{i_2}, b_{i_4})$ is not a core for any i_1, i_2, i_3, i_4 Blocking variables are exchangeable: cores are defined by the number of them, Intuition: not the identity of them Any $\kappa \subset \mathcal{F}_{B}$ s.t $|\kappa| = (n - r) + 1$ is a core. IHS needs to extract all $\binom{n}{(n-r)+1}$ of them.

More Specifically

$$\begin{split} \mathcal{F}_{H} &= \left\{ \mathrm{CNF}(\sum_{i=1}^{n} b_{i} \geq r) \right\} \\ \mathcal{F}_{B} &= \{b_{1}, \ldots, b_{n}\} \end{split}$$

Opt. cost = r

Let C be any set of cores. Assume $S \notin C$ for some |S| = n - r + 1

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Weakness shown in practice

https://maxsat-evaluations.github.io/2019/rankings.html

Benchmarks	MaxHS	MaxHS 4.0	RC2
drmx-atmostk (W) (11)	3	11	11
drmx-atmostk (UW) (17)	3	17	17

- ▶ Results from 2019 MSE and our paper.
- ▶ MaxHS: an IHS solver w/o abstract cores
- ▶ MaxHS 4.0 an IHS solver with abstract cores
- ▶ RC2: the best performing solver in the 2020 MaxSat evaluation

Research Question

Does there exists a compact representation of large sets of cores that IHS can reason over?

Idea: What happens if we introduce literals that count the number of blocking variables set to true?

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$$\begin{split} AB &= \{b_1,\ldots,b_5\} \subset \mathcal{F}_B \\ \mathcal{F}_H &= \left\{ \mathrm{CNF}(\sum_{i=1}^n b_i \geq r) \right\} \\ \mathcal{F}_B &= \{b_1,\ldots,b_n\} \end{split}$$

Idea: What happens if we introduce literals that count the number of blocking variables set to true?

(similar to variables that have been successfully used in core-guided solvers)

$$\begin{split} \mathcal{F}_{H} &= \left\{ \mathrm{CNF}(\sum_{i=1}^{n} b_{i} \geq r) \right\} \\ \mathcal{F}_{B} &= \{ b_{1}, \dots, b_{n} \} \\ \mathrm{s}^{AB}[\mathrm{i}] \leftrightarrow \left(\sum_{b \in AB} b \geq \mathrm{i} \right) \end{split}$$

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Note: Can be encoded as CNF

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$$\begin{split} AB &= \{b_1, \dots, b_5\} \subset \mathcal{F}_B \\ Define \; s^{AB}[i] \\ Consider: \; \; (b_7, s^{AB}[3], b_n) \end{split}$$

$$\begin{aligned} s^{AB}[3] &= 1 \text{ means} \\ \sum_{b \in S} b \geq 1 = (\bigvee_{b \in S} b) \\ \text{for any } S \subset AB \text{ with} \\ |S| &= 3(=5-3+1) \end{aligned}$$

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Idea: What happens if we introduce literals that count the number of blocking variables set to true?

(similar to variables that have been successfully used in core-guided solvers)

Terminology: AB is an abstraction set $s^{AB}[i]$ is an abstraction variable The definition of $s^{AB}[i]$ is $s^{AB}[i] \leftrightarrow (\sum_{b \in AB} b \ge i)$
$$\begin{split} AB &= \{b_1,\ldots,b_5\} \subset \mathcal{F}_B \\ Define \; s^{AB}[i] \\ Consider: \; \; (b_7,s^{AB}[3],b_n) \end{split}$$

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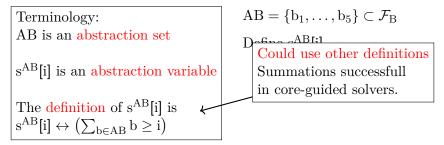
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AB is an abstraction set $AB = \{b_1, \dots, b_5\} \subset \mathcal{F}_B$
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 $s^{AB}[i] \leftrightarrow (\sum_{b \in AB} b \ge i)$ Consider: $(b_7, s^{AB}[3], b_n)$

Abstract Core:

a clause over abstraction and blocking variables that is entailed by \mathcal{F}_{H} and the definitions of abstraction variables

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Abstract Core:

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Abstract cores are expressive

Proposition

An abstract core containing the abstraction variables $\{s^{AB^1}[j_1],\ldots,s^{AB^k}[j_k]\}$ is equivalent to the conjunction of

$$\prod_{i=1}^k \binom{|AB^i|}{|AB^i|-j_i+1}$$

regular cores.

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regular cores.

Two Questions remain:

- 1. How to compute abstraction sets?
- 2. How to extract and reason over abstract cores in IHS?

Ideally

Identify a set $S \subset \mathcal{F}_B$ of exchangeable blocking variables.

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In practice

Form abstraction sets over blocking variables that appear frequently in cores together. LB: 0









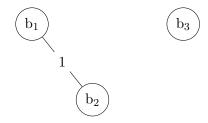


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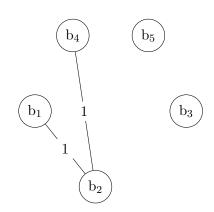


Core: (b_2, b_4) LB: 0

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Identify a set $S \subset \mathcal{F}_B$ of exchangeable blocking variables.

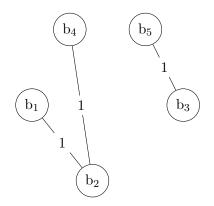
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Core: (b_3, b_5) LB: 0

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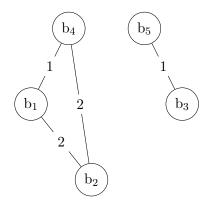


Core: (b_1, b_2, b_4) LB: 0

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Identify a set $S \subset \mathcal{F}_B$ of exchangeable blocking variables.

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Ideally

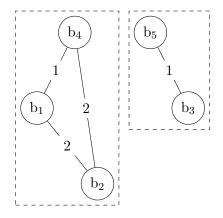
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In practice

Form abstraction sets over blocking variables that appear frequently in cores together.

Recall: IHS needs to increase LB to optimum

Clustering LB: 0



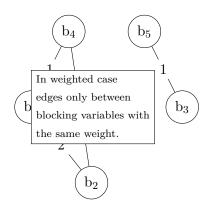
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Form abstraction sets over blocking variables that appear frequently in cores together.

Recall: IHS needs to increase LB to optimum



$$\mathcal{F}_{H} = \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\}$$
 Abstract-IHS (\mathcal{F})

 $\mathcal{F}_B=\{b_1,b_2,b_3,b_4\}$

$$\mathcal{F}_{H} = \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\}$$

Abstract-IHS
$$(\mathcal{F})$$

Initialize

 $\mathcal{F}_B=\{b_1,b_2,b_3,b_4\}$

 $UB = \infty \qquad LB = 0$ $\mathcal{AB} = \emptyset$ $C = \emptyset$ $bestsol = \varnothing$

$$\mathcal{F}_{H} = \{(b_1, b_2), (b_2, b_3), (b_3, b_4)\}$$

Abstract-IHS (\mathcal{F})

 $\mathcal{F}_B=\{b_1,b_2,b_3,b_4\}$

Initialize while LB < UB

 $UB = \infty \qquad LB = 0$ $\mathcal{AB} = \emptyset$ $C = \emptyset$ $bestsol = \emptyset$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ &\bigwedge_{i=1}^{2}\operatorname{CNF}\left((b_{2}+b_{3}\geq i)\rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB}

$$\begin{split} UB &= \infty \qquad LB = 0 \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \emptyset \\ bestsol &= \varnothing \end{split}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}), \\ &\bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2} + b_{3} \geq i) \rightarrow s^{AB}[i]\right) \} \\ &\mathcal{F}_{B} &= \left\{b_{1}, b_{2}, b_{3}, b_{4}\right\} \end{split}$$

hs = Min-Abs $(\mathcal{F}_{\mathrm{B}}, \emptyset, \mathcal{AB})$

Abstract-IHS (\mathcal{F})

Initialize while LB < UB Update \mathcal{AB} Compute min-cost hitting set hs

$$\begin{split} & \sum_{b \in AB} b - k \cdot s^{AB}[k] \geq 0 \\ & \sum_{b \in AB} b - |AB| \cdot s^{AB}[k] < k \\ & \text{Min-Abs } (\mathcal{F}_B, C, \mathcal{AB}): \\ & \text{minimize: } \sum_{b \in \mathcal{F}_B} b \\ & \text{subject to: } \sum_{b \in \kappa} b \geq 1 \ \forall \kappa \in C \\ & (\sum_{b \in AB} b \geq k) \leftrightarrow s^{AB}[k] \ \forall AB \in \mathcal{AB} \\ & \text{return: } \{b \mid b \text{ set to 1 in opt. soln} \} \end{split}$$

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 $hs = \emptyset$

Abstract-IHS (\mathcal{F})

Initialize while LB < UB Update \mathcal{AB} Compute min-cost hitting set hs Update LB

 $UB = \infty \qquad LB = |\emptyset|$ $\mathcal{AB} = \{AB = \{b_2, b_3\}\}$ $C = \emptyset$ $bestsol = \emptyset$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ &\bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2}+b_{3} \geq i) \rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

$$\begin{split} hs &= \emptyset \\ \mathcal{A} &= ABSTRACT(\mathcal{F}_B, hs, \mathcal{AB}) \\ &= \{b_1, s^{AB}[1], b_4\} \\ AB &= \{b_2, b_3\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UB Update \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions

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\begin{array}{l} \operatorname{ABSTRACT}(\mathcal{F}_{B}, \operatorname{hs}, \mathcal{AB}) \\ \mid \mathcal{A} \leftarrow \{ b \, | \, b \in \mathcal{F}_{B} - \operatorname{hs} \} \\ \text{foreach } AB \in \mathcal{AB} \ \operatorname{do} \\ \mid \mathcal{A} \leftarrow \mathcal{A} - \{ b \, | \, b \in AB \} \\ \mid \mathcal{A} \leftarrow \mathcal{A} \cup \{ s^{AB} [ |AB \cap \operatorname{hs}| + 1] \} \\ \text{return } \mathcal{A} \end{array}
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$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}), \\ & \bigwedge_{i=1}^{2} \operatorname{CNF} \left((b_{2} + b_{3} \geq i) \rightarrow s^{AB}[i] \right) \} \\ & \mathcal{F}_{B} &= \left\{ b_{1}, b_{2}, b_{3}, b_{4} \right\} \end{split}$$

sat-assume(
$$\mathcal{F}_{H}, \neg \mathcal{A}$$
)
 $\mathcal{A} = \{b_1, s^{AB}[1], b_4\}$
 $K = \{\}$

Abstract-IHS
$$(\mathcal{F})$$

Initialize while LB < UB Update \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT

$$\begin{split} UB &= \infty \qquad LB = 0 \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \emptyset \\ bestsol &= \varnothing \end{split}$$

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$$\begin{split} & \operatorname{sat-assume}(\mathcal{F}_H, \neg \mathcal{A}) \\ & \mathcal{A} = \{ b_1, s^{AB}[1], b_4 \} \\ & \operatorname{K} = \{ (s^{AB}[1]) \} \end{split}$$

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sat-assume(
$$\mathcal{F}_{H}, \neg \mathcal{A}$$
)
 $\mathcal{A} = \{b_1, b_4\}$
 $K = \{(s^{AB}[1])\}$
 $\tau = \{\neg b_1, b_2, b_3, \neg b_4\}$

 $UB = \infty \qquad LB = 0$ $\mathcal{AB} = \{AB = \{b_2, b_3\}\}$ $C = \emptyset$ $bestsol = \emptyset$

Abstract-IHS (\mathcal{F})

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$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ &\bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2}+b_{3} \geq i) \rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

$$\begin{aligned} \mathbf{K} &= \{ (\mathbf{s}^{\mathrm{AB}}[1]) \} \\ \tau &= \{ \neg \mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3, \neg \mathbf{b}_4 \} \end{aligned}$$

 $UB = cost(\tau) \qquad LB = 0$ $\mathcal{AB} = \{AB = \{b_2, b_3\}\}$ $C = \emptyset$ $bestsol = \{\neg b_1, b_2, b_3, \neg b_4\}$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB

Min-Abs $(\mathcal{F}_{B}, C, \mathcal{AB})$: minimize: $\sum_{b \in \mathcal{F}_{B}} b$ subject to: $\sum_{b \in \kappa} b \ge 1 \forall \kappa \in C$ $(\sum_{b \in AB} b \ge k) \leftrightarrow s^{AB}[k] \forall AB \in \mathcal{AB}$ return: $\{b \mid b \text{ set to 1 in opt. soln}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ &\bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2}+b_{3} \geq i) \rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

$$\mathbf{K} = \{ (\mathbf{s}^{AB}[1]) \}$$

$$\tau = \{ \neg \mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3, \neg \mathbf{b}_4 \}$$

UB = 2 LB = 0 $\mathcal{AB} = \{AB = \{b_2, b_3\}\}$ $C = \{(s^{AB}[1])\}$ $bestsol = \{\neg b_1, b_2, b_3, \neg b_4\}$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ & \bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2}+b_{3} \geq i) \rightarrow s^{AB}[i]\right) \} \\ & \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

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$$\begin{split} UB &= 2 & LB &= 0 \\ \mathcal{AB} &= \{AB &= \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1])\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

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Initialize while LB < UB Update *AB* Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

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hs = Min-Abs
$$(\mathcal{F}_{B}, \{(s^{AB}[1])\}, \mathcal{AB})$$

Abstract-IHS (\mathcal{F})

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 $hs=\{b_2\}$

$$\begin{split} UB &= 2 & LB = |\{b_2\}| \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1])\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UB Update \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

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$$\begin{split} hs &= \{b_2\} \\ \mathcal{A} &= \{b_1, s^{AB}[2], b_4\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

 $\begin{array}{l} \text{ABSTRACT}(\mathcal{F}_{\text{B}}, \text{hs}, \mathcal{AB}) \\ & \mid \mathcal{A} \leftarrow \{ b \, | \, b \in \mathcal{F}_{\text{B}} - \text{hs} \} \\ & \text{foreach AB} \in \mathcal{AB} \text{ do} \\ & \mid \mathcal{A} \leftarrow \mathcal{A} - \{ b \, | \, b \in \text{AB} \} \\ & \mid \mathcal{A} \leftarrow \mathcal{A} \cup \{ s^{\text{AB}}[|\text{AB} \cap \text{hs}| + 1] \} \\ & \text{return } \mathcal{A} \end{array}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}), \\ & \bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2} + b_{3} \geq i) \rightarrow s^{AB}[i]\right) \} \\ & \mathcal{F}_{B} &= \left\{b_{1}, b_{2}, b_{3}, b_{4}\right\} \end{split}$$

sat-assume(
$$\mathcal{F}_{H}, \neg \mathcal{A}$$
)
 $\mathcal{A} = \{b_1, s^{AB}[2], b_4\}$
 $K = \{\}$

$$UB = 2 LB = 1$$

$$\mathcal{AB} = \{AB = \{b_2, b_3\}\}$$

$$C = \{(s^{AB}[1])\}$$

$$bestsol = \{\neg b_1, b_2, b_3, \neg b_4\}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}), \\ & \bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2} + b_{3} \geq i) \rightarrow s^{AB}[i]\right) \} \\ & \mathcal{F}_{B} &= \left\{b_{1}, b_{2}, b_{3}, b_{4}\right\} \end{split}$$

$$\begin{split} &\operatorname{sat-assume}(\mathcal{F}_H, \neg \mathcal{A}) \\ &\mathcal{A} = \{ b_1', \underline{s^{AB}}[2], b_4' \} \\ &\operatorname{K} = \{ (b_1, \underline{s^{AB}}[2], b_4) \} \end{split}$$

$$UB = 2 LB = 1$$

$$\mathcal{AB} = \{AB = \{b_2, b_3\}\}$$

$$C = \{(s^{AB}[1])\}$$

$$bestsol = \{\neg b_1, b_2, b_3, \neg b_4\}$$

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$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ &\bigwedge_{i=1}^{2}\operatorname{CNF}\left((b_{2}+b_{3}\geq i)\rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

$$\begin{split} \mathbf{K} &= \{ (\mathbf{b}_1, \mathbf{s}^{AB}[2], \mathbf{b}_4) \} \\ \tau &= \{ \neg \mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3, \neg \mathbf{b}_4 \} \end{split}$$

$$\begin{split} UB &= 2 & LB = 1 \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1])\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

Min-Abs $(\mathcal{F}_{B}, C, \mathcal{AB})$: minimize: $\sum_{b \in \mathcal{F}_{B}} b$ subject to: $\sum_{b \in \kappa} b \ge 1 \forall \kappa \in C$ $(\sum_{b \in AB} b \ge k) \leftrightarrow s^{AB}[k] \forall AB \in \mathcal{AB}$ return: $\{b \mid b \text{ set to 1 in opt. soln}\}$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}), \\ &\bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2} + b_{3} \geq i) \rightarrow s^{AB}[i]\right)\} \\ &\mathcal{F}_{B} &= \left\{b_{1}, b_{2}, b_{3}, b_{4}\right\} \end{split}$$

$$\begin{split} & K = \{ (b_1, s^{AB}[2], b_4) \} \\ & \tau = \{ \neg b_1, b_2, b_3, \neg b_4 \} \end{split}$$

$$\begin{split} UB &= 2 & LB = 1 \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1]), (b_1, s^{AB}[2], b_4)\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ &\bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2}+b_{3} \geq i) \rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

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Initialize while LB < UB Update *AB* Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

$$\begin{split} UB &= 2 & LB = 1 \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1]), (b_1, s^{AB}[2], b_4)\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1}, b_{2}), (b_{2}, b_{3}), (b_{3}, b_{4}), \\ & \bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2} + b_{3} \geq i) \rightarrow s^{AB}[i]\right) \} \\ & \mathcal{F}_{B} &= \left\{b_{1}, b_{2}, b_{3}, b_{4}\right\} \end{split}$$

 $hs = Min-Abs (\mathcal{F}_B, C, \mathcal{AB})$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C

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 $hs = \{b_2, b_3\}$

Abstract-IHS (\mathcal{F})

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$$\begin{split} UB &= 2 & LB = |\{b_2, b_3\}| \\ \mathcal{AB} &= \{AB = \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1]), (b_1, s^{AB}[2], b_4)\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

$$\begin{split} \mathcal{F}_{H} &= \{(b_{1},b_{2}),(b_{2},b_{3}),(b_{3},b_{4}),\\ & \bigwedge_{i=1}^{2} \operatorname{CNF}\left((b_{2}+b_{3}\geq i) \rightarrow s^{AB}[i]\right)\}\\ \mathcal{F}_{B} &= \left\{b_{1},b_{2},b_{3},b_{4}\right\} \end{split}$$

 $hs = \{b_2, b_3\}$

$$\begin{split} UB &= 2 & LB &= 2 \\ \mathcal{AB} &= \{AB &= \{b_2, b_3\}\} \\ C &= \{(s^{AB}[1]), (b_1, s^{AB}[2], b_4)\} \\ bestsol &= \{\neg b_1, b_2, b_3, \neg b_4\} \end{split}$$

Abstract-IHS (\mathcal{F})

Initialize while LB < UBUpdate \mathcal{AB} Compute min-cost hitting set hs Update LB Set up assumptions Extract cores until SAT Update UB Add cores to C return bestsol

Effects of Abstract Cores

Abstract cores improve IHS in theory

In theory

For each (unweighted) MaxSAT instance, there exists an abstraction set with which Abstract-IHS terminates with a polynomial number of cores.

Abstract cores improve IHS in theory

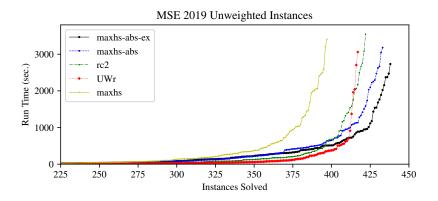
In theory

For each (unweighted) MaxSAT instance, there exists an abstraction set with which Abstract-IHS terminates with a polynomial number of cores.

.. however

- ▶ trade of between expressivity and overhead
- abstraction sets should be large enough to benefit IHS without inducing a lot of overhead.

.. and practice

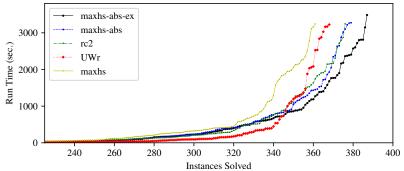


▶ maxhs: basic IHS (MaxHS

[Davies and Bacchus, 2013b, 2011])

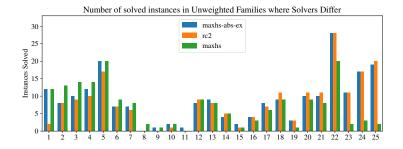
- maxhs-abs: maxhs with abstract core reasoning
- maxhs-abs-ex: maxhs-abs with additional heuristics.
- rc2 and UWr best performing solvers in 2019 MSE [Ignatiev, Morgado, and Marques-Silva, 2019; Karpinski and Piotrów, 2019]

Results - Weighted



MSE 2019 Weighted Instances

by benchmark family



Summary

Implicit hitting sets for MaxSat

- MaxSAT Low-level constraint language: weighted Boolean combinations of binary variables
 Gives tight control over how exactly to encode problem
- Exact optimization: provably optimal solutions
- ▶ IHS MaxSat solvers:
 - ▶ build on top of highly efficient SAT and IP solver technology
 - ▶ one of the most successful approaches to complete MaxSat

Implicit hitting sets for MaxSat

- MaxSAT Low-level constraint language: weighted Boolean combinations of binary variables
 Gives tight control over how exactly to encode problem
- Exact optimization: provably optimal solutions
- ▶ IHS MaxSat solvers:
 - build on top of highly efficient SAT and IP solver technology
 - ▶ one of the most successful approaches to complete MaxSat
 - ... even before the addition of abstract cores.

Further Reading and Links

Surveys

▶ "Maximum Satisfiability" by Bacchus, Järvisalo & Martins

- Chapter in vol. 2 of Handbook of Satisfiability
- Now available.

MaxSat Evaluations https://maxsat-evaluations.github.io Most recent report: [Bacchus, Järvisalo, and Martins, 2019]

Thank you for attending!

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