

Certifying Automated Reasoning

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Automated reasoning

Significant progress in last couple of decades on combinatorial solvers

- Boolean satisfiability (SAT) & modulo theories (SMT), solving and optimization [Biere, Heule, van Maaren, and Walsh, 2021]
- Constraint programming [Rossi, van Beek, and Walsh, 2006]
- Pseudo-boolean (0-1 integer linear programming) [Elffers and Nordström, 2020].

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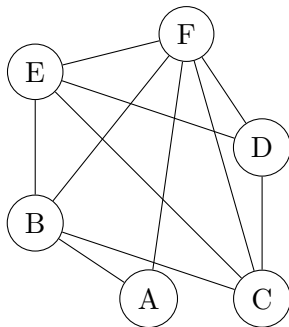
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scheduling
learning DAGs
kidney matching
cancer treatment
allocation of education
hardware and software verification
bounded model checking
allocation of work
air traffic control
healthcare logistics

Example problem

Maximum Clique

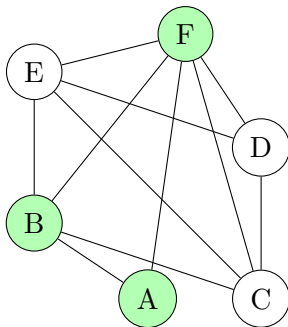
Decision problem: Is there clique of size 3?



Example problem

Maximum Clique

Decision problem: Is there clique of size 3? **yes**

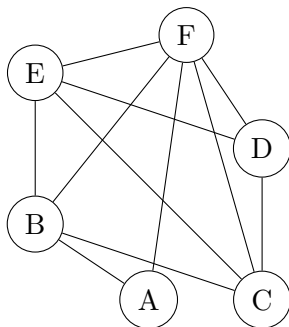


Example problem

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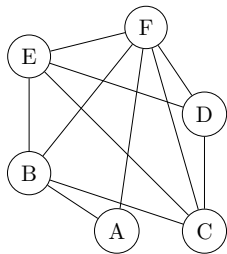
Decision problem: Is there clique of size 3? **yes**

Optimization problem: What is the size of the largest clique?



Automated Reasoning

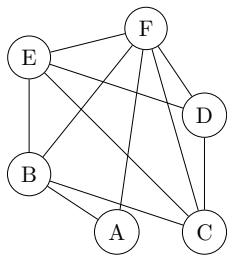
for solving maximum clique



Problem instance

Automated Reasoning

for solving maximum clique



Maximize: $x_A + x_B + x_C + x_D + x_E + x_F$

subject to:

$$(1 - x_A) + (1 - x_C) \geq 1$$

$$(1 - x_D) + (1 - x_B) \geq 1$$

\vdots

$$x_j \in \{0, 1\} \quad \forall j$$

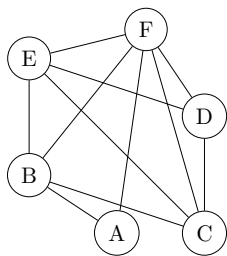
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Problem instance

Constraint encoding

Automated Reasoning

for solving maximum clique



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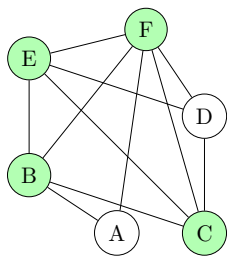
Problem instance

Constraint encoding

Solution to constraints
Green=1, Red=0

Automated Reasoning

for solving maximum clique



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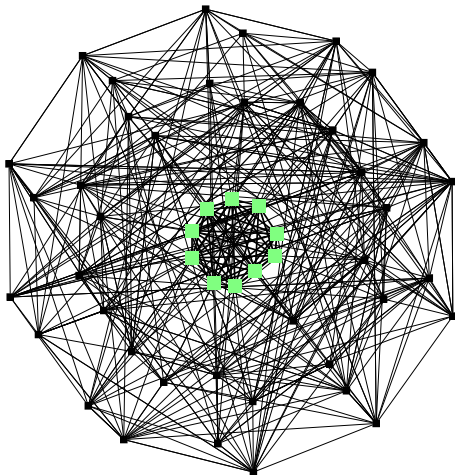
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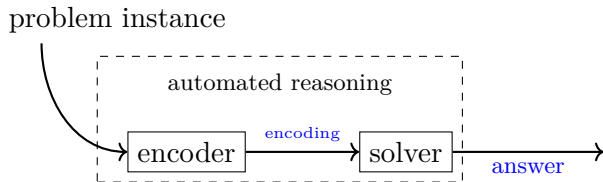
The main question of the day

Can we trust the answer?



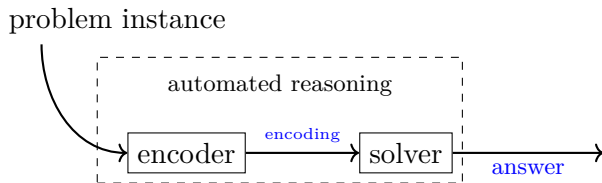
Automated reasoning

in general



Automated reasoning

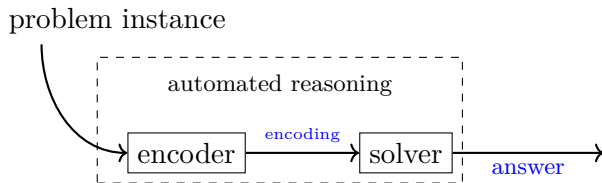
in general



3 main approaches toward trustworthiness:

Automated reasoning

in general

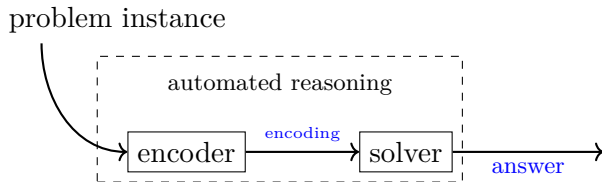


3 main approaches toward trustworthiness:

testing

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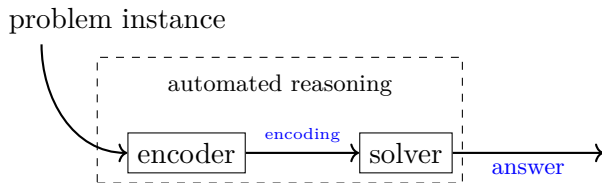
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formal verification

Automated reasoning

in general



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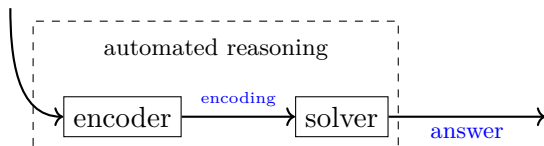
formal verification

proof logging

Proof Logging

[Järvisalo, Heule, and Biere, 2012; Wetzler, Heule, and Jr., 2014; Heule, 2021; van Doornmalen, Eifler, Gleixner, and Hojny, 2023; Bogaerts, Gocht, McCreesh, and Nordström, 2022]

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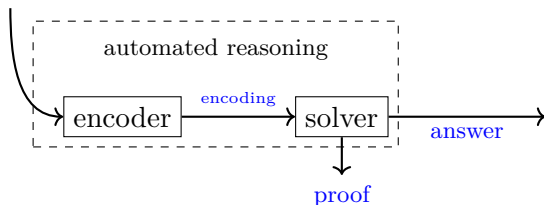
Desiderata of proof format

- powerful
- simple

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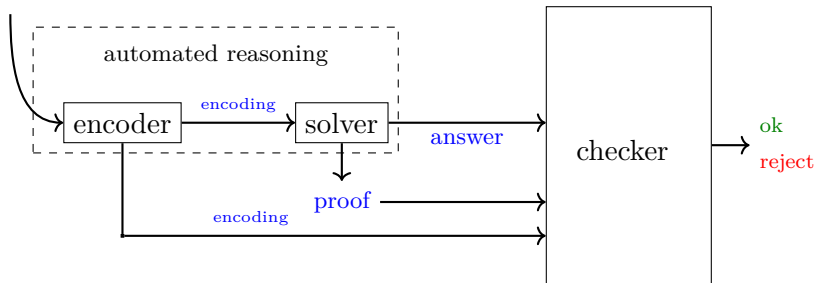
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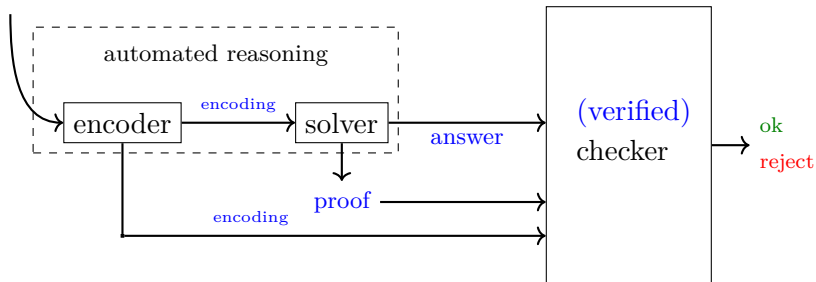
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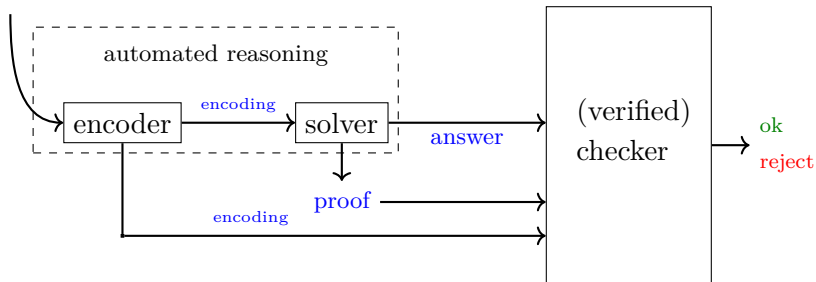
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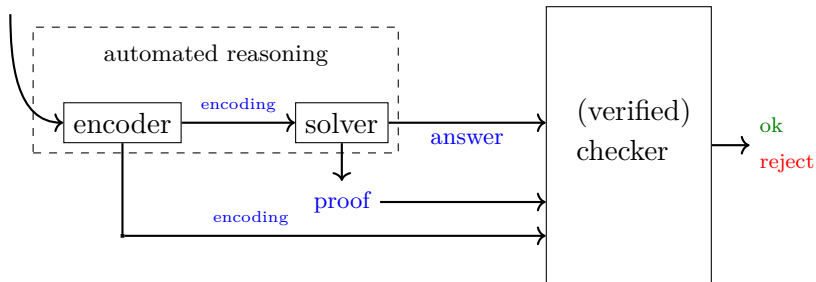
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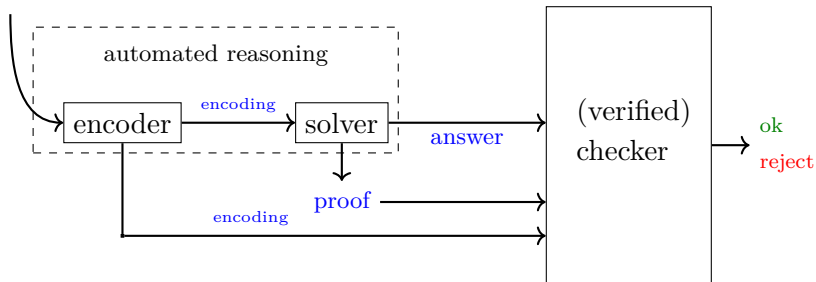
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Redundance-based proofs

Concrete Constraints

Propositional Logic, SAT, MaxSAT

- Instance:
 - ▶ Set of clauses, (CNF formula)
 - ▶ a linear objective function cost
- Find assignment τ that:
 - ▶ satisfies all clauses and
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$$F = \{(b_1 \vee x), (\neg x \vee b_2), \\ (b_2 \vee y), (\neg y, b_3)\}$$

$$\text{cost} \equiv 2b_1 + 4b_2 + b_3$$

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$$\begin{aligned}\tau(y) &= \tau(b_1) = \tau(b_3) = 1 \\ \tau(x) &= \tau(b_2) = 0\end{aligned}$$

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$$\text{cost}(\tau) = 3$$

Clause Redundancy

[Järvisalo, Heule, and Biere, 2012; Heule, Kiesl, and Biere, 2020; Ihalainen, Berg, and Järvisalo, 2022]

Definition

Clause C is redundant for formula F and objective cost if

$$\text{minimum-cost}(F) = \text{minimum-cost}(F \wedge C)$$

(wrt. cost)

equisatisfiability a special case

Example:

$$(x \vee b_1) \wedge (\neg x \vee b_2)$$

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$(\neg b_2)$ is redundant

$(\neg b_1)$ is **not** redundant

Characterizing redundancy

[Heule, Kiesl, and Biere, 2020; Ihalainen, Berg, and Jarvisalo, 2022]

(informal) Theorem

C redundant for F and cost iff there exists a set of literals L_C that fixes any solution τ of F that falsifies C without increasing its cost.

Example

$$F = (x \vee b_1) \wedge (\neg x \vee b_2 \vee b_1)$$

$$\text{cost} = b_1 + 2b_2$$

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If τ satisfies F but falsifies C
then assigning $b_1 = 1$, $b_2 = 0$ and
the rest according to τ
satisfies $F \wedge C$ with cost less than τ .

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Example

$$F = (x \vee b_1) \wedge (\neg x \vee b_2 \vee b_1) \wedge F' \leftarrow$$

F' does not
contain $b_1, b_2, \neg b_1$ or $\neg b_2$

$$\text{cost} = b_1 + 2b_2$$

$C = (\neg b_2)$ is redundant

$$L_C = \{\neg b_2, b_1\}$$

Note: adding redundant clauses might change the set of solutions

A (very simplified) redundancy-based proof

e.g. [Heule, Kiesl, and Biere, 2020; Bogaerts, Gocht, McCreesh, and Nordström, 2022]

A proof for $F = \{C_1, \dots, C_n\}$ and cost is a sequence:

$$C_1, C_2, \dots, C_n, C_{n+1}, \dots \square \text{ =empty clause}$$

s.t. each C_{n+t} is either:

- redundant wrt. $C_1 \wedge \dots \wedge C_{n+t-1}$, or
- $\text{cost} < \text{cost}(\tau)$ for a solution τ of $C_1 \wedge \dots \wedge C_{n+t-1}$.

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The proof establishes:

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redundancy-based proof systems are strong
need to be careful with deletion

Redunancy for simulating solver reasoning

Subsumed Literal Elimination

[Berg, Saikko, and Järvisalo, 2016; Korhonen, Berg, Saikko, and Järvisalo, 2017]

Assume:

- i) b_2 appears at least in the same clauses as b_1 .
- ii) the coefficient of b_2 in cost is at most the coefficient of b_1 .

Then fix $b_2 = 0$ and simplify.

Reasoning

$$\text{cost} = b_1 + 2b_2$$

$$(x \vee b_1) \wedge (\neg x \vee b_2 \vee b_1)$$

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Redundancy

$$(x \vee b_1) \wedge (\neg x \vee b_2 \vee b_1)$$

↓

$$\text{add } (\neg b_2)$$

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Redundancy

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$$\text{add } (\neg b_2)$$

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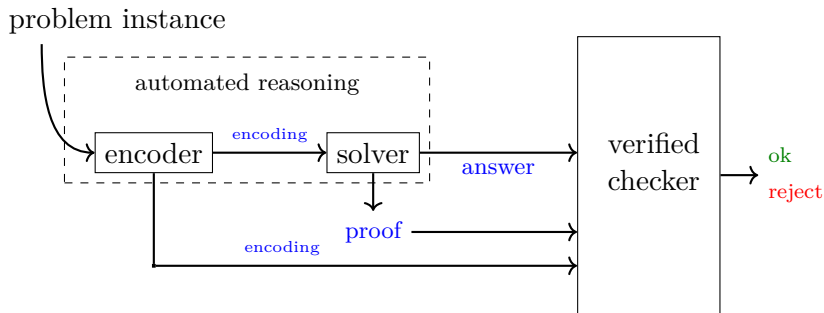
↓

$$\text{remove } (\neg x \vee b_1 \vee b_2)$$

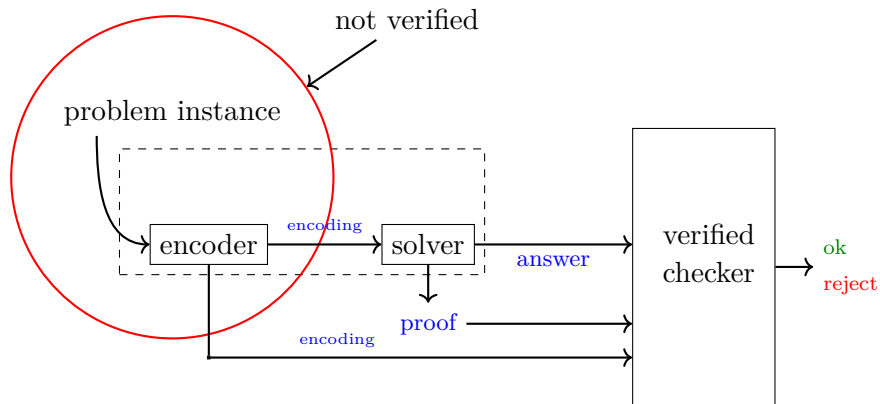
↓

What do we need to trust?

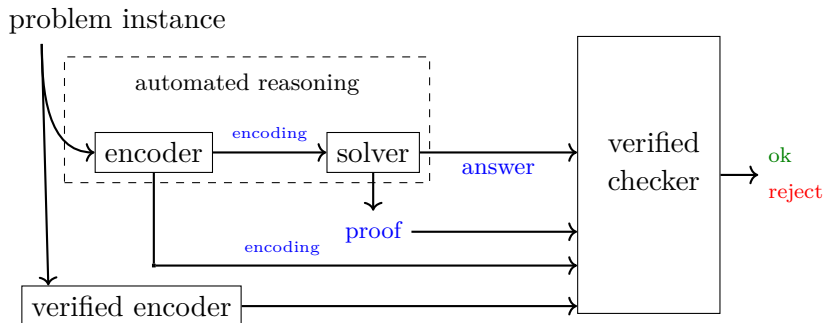
Recap: Certified Automated Reasoning



What about the encoding?



What about the encoding?



- problem-specific verified encoder can prove the right properties of the encoding

What are these right properties?

[Gocht, McCreesh, Myreen, Nordström, Oertel, and Tan, 2024; Ihalainen, Oertel, Tan, Berg, Järvisalo, Myreen, and Nordström, 2024]

$$\begin{aligned} \text{is_clique } vs (v, e) &\stackrel{\text{def}}{=} \\ &vs \subseteq \{ 0, 1, \dots, v-1 \} \wedge \\ &\forall x y. x \in vs \wedge y \in vs \wedge x \neq y \Rightarrow \text{is_edge } e x y \\ \text{max_clique_size } g &\stackrel{\text{def}}{=} \max_{\text{set}} \{ \text{card } vs \mid \text{is_clique } vs g \} \end{aligned}$$

What are we trusting now?

- e.g. HOL model of verified checkers and correspondence to real system
- HOL4 theorem prover, including logic, implementation, and execution environment [Shad and Norrish, 2008]

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Proof logging in the Constraint Reasoning and Optimization Group

Earlier

- Fundamentals of redundancy notions in boolean decision problems (SAT) [Järvisalo, Heule, and Biere, 2012]

Currently

- Fundamentals of redundancy notions in boolean optimization (MaxSAT) [Berg and Järvisalo, 2019; Ihalainen, Berg, and Järvisalo, 2022]
- Certifying solvers and preprocessors [Ihalainen, Oertel, Tan, Berg, Järvisalo, Myreen, and Nordström, 2024; Berg, Bogaerts, Nordström, Oertel, and Vandesande, 2023]
- Multiobjective optimization [Jabs, Berg, Ihalainen, and Järvisalo, 2023]

Conclusion

Proof logging in automated reasoning:

- Guarantees correctness of results
- Supports development of increasingly complex reasoning into solvers.
- Provides audibility to third parties without access to the solver.

Open Challenges

- Practical scaling.
- Proof logging e.g. PSPACE-complete problems.
- Proving bounds on the proof systems used.

Conclusion

Proof logging in automated reasoning:

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Open Challenges

- Practical scaling.
- Proof logging e.g. PSPACE-complete problems.
- Proving bounds on the proof systems used.

I am hiring someone to work on these kinds of topics!

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